

**Flight Test Results
of the
Micro-Tech-Sensor for
Attitude and Orbit Determination**

astrium

an Airbus Group Company with the Airbus logo

C.T.F. Kuhl¹⁾
M. Mehl¹⁾
H. Diehl²⁾
E. Gottzein¹⁾

¹⁾
Astrium GmbH
D-81663 München
Tel. +49-89-60727284
Fax +49-89-607-28675
email: christophe.kuehl@astriumspace.com

²⁾
EADS Deutschland GmbH

Preview

- State of the Art Sensors and Systems
- The New Sensor Principle
- Investigations
 - Analysis
 - Simulation & Experiments
- **Results taken from the MTS-AOMS Experiment on MITA**
- Performance Prediction
- Conclusions and Recommendations

1) Flight Test Results for the Micro-Tech-Sensor for Attitude and Orbit Determination
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State of the Art Sensors and Systems

Example GEO Communication Satellite

Attitude Determination: 3 Sensor-types
Orbit Determination: Groundstation

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Proposition of a New Sensor Principle

Based on Active Pixel (APS)- and MEMS- Technology

Special Features:

- On-Board-Autonomous Determination of
 - Attitude
 - Position
 - Rate
 Realized in a **Single Sensor!**
- Universal Application in MEO, LEO, GEO
- Reduction of
 - Mass (approx. 1,5 kg* vs. 10 kg) MITA Experiment
 - Energy (approx. 7,5 W* vs. 15 W)
 - Complexity (* : Data taken from Experimental Setup)

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New Sensor's Principle (Optics)

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Investigations

Major emphasis in this presentation:

- Star- Centroiding accuracies and their consequences
- Algorithm- Design for Earth- Center determination in the Visual Regime
- Behavior of MicroSystemTechnology in Space

Reference Data Sets were obtained through

- Laboratory-experiments
- Field-experiments (Max-I-Rainer-Alm)
- Meteosat data (courtesy of Eumetsat)
- Flight-experiment (MITA)

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Investigations: Centroiding

Peculiarities due to

- APS- Technology exhibiting low fillfactors
- Large field-of-view

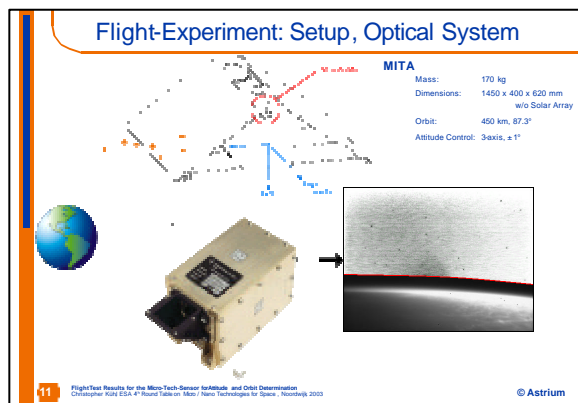
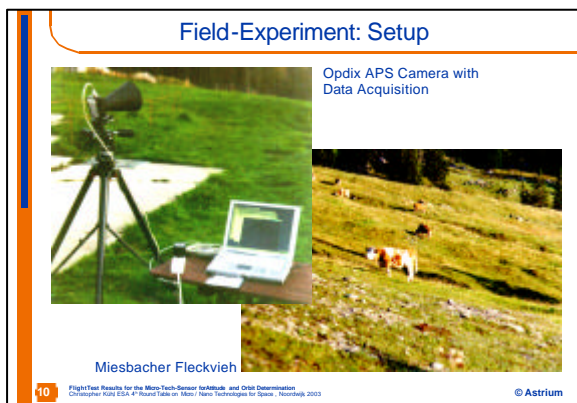
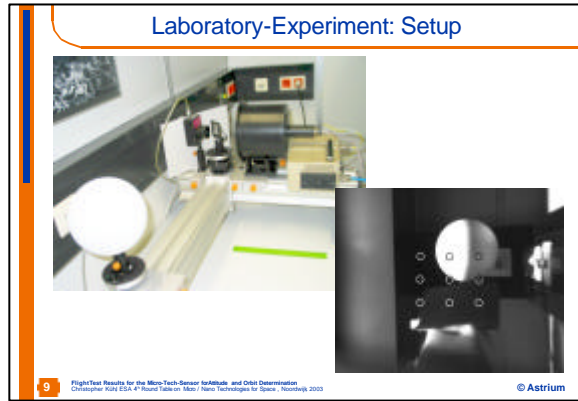
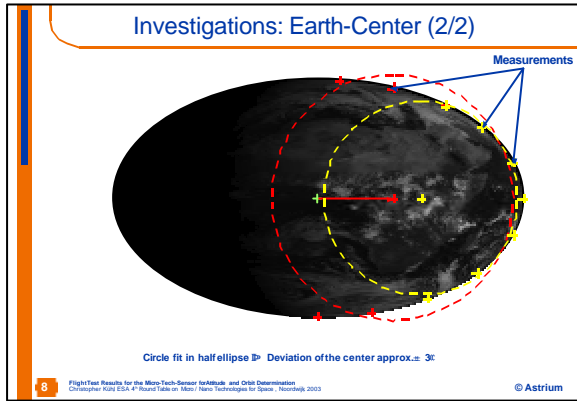
Detector-area approx. 80 μm x 80 μm

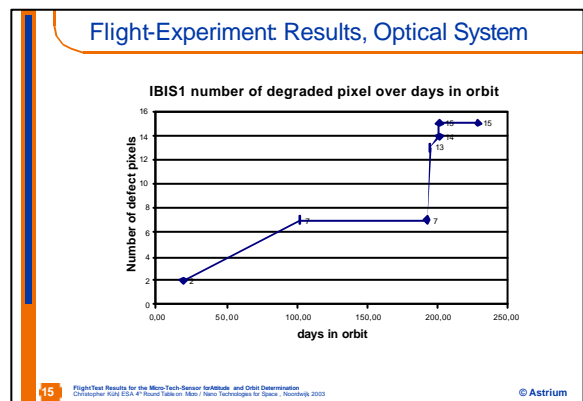
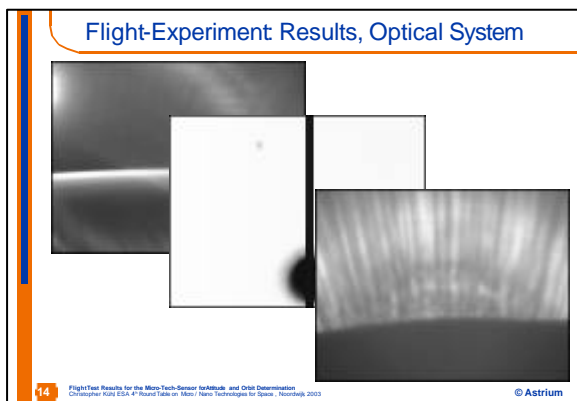
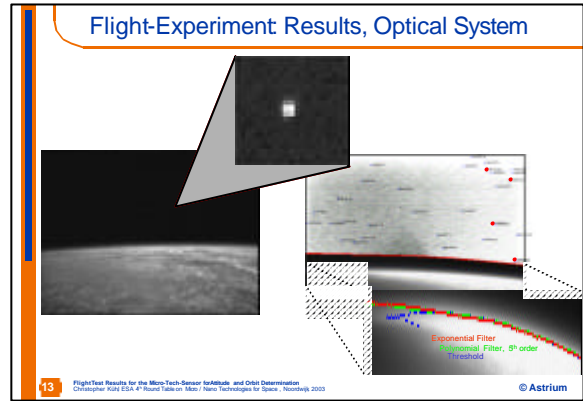
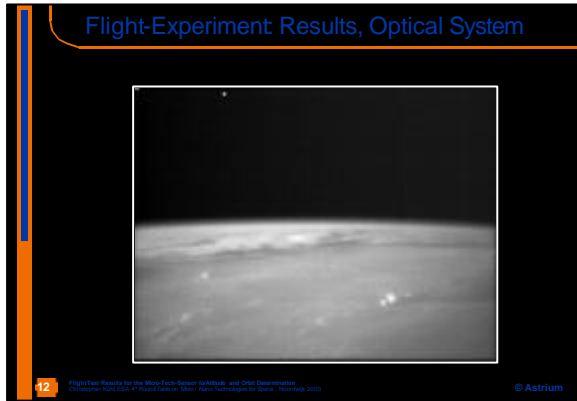
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Investigations: Earth-Center (1/2)

Example: GEO

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Flight Experiment: Setup, MEMS-Components

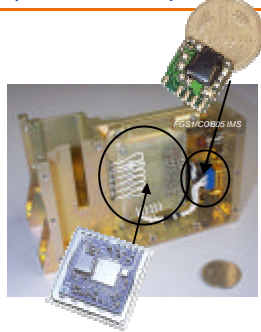
Redundancy by introduction of

Magnetometers (e.g. FHG)

Increased Robustness and Accuracy of Attitude (EMF-Model)– and Position (Filtering)

Rate-sensors (e.g. Bosch)

Increased Robustness and Accuracy of Rate-Signal



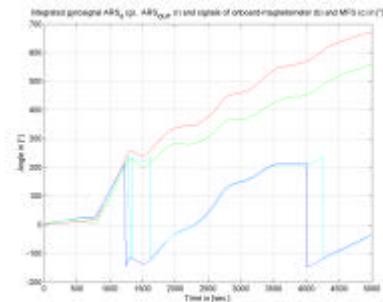
Bosch DRS MM 1.0

16

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Flight-Experiment Results, MEMS-Components



17

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Performance Prediction

Errors **Geometrically Additive** in First Order Approximation

- Attitude Accuracies
 - Earth-Center approx. 360'', 1 σ (goal: 3 σ)
 - Single Star-Centroiding approx. 10'', 1 σ (goal: 3 σ)
(calibrated system)
 - Inertial attitude approx. 5.3'' (25''), 1 σ (goal: 3 σ)
(5 observed stars)
- Orbital Radius and 3D-Position Accuracy:
 - GEO, GTO, LEO(SSO) approx. 5 km, 1 σ (goal: 3 σ)
(after 2-3 orbits)

(→ Limitation of Accuracy Primarily due to Determination-Inaccuracies of Earth-Center)

Attitude & Orbit Accuracies Sufficient for Most Missions!

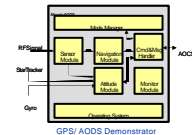
18

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Conclusion

- Functionality of the proposed Sensor was successfully demonstrated
- Attitude & Orbit Accuracies meet requirements for a wide range of satellite missions
- Sensor applicable for orbits around other planets by software-adaptation
- Algorithms can be adapted for use in the GPS/AODS Demonstrator (ESTEC Contract No. 16634/02/NL/US)



GPS/ AODS Demonstrator

19

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Recommendations and Future Work

- Procedures for on-board autonomous calibration and use of available *a priori* information for further improvement of the system's accuracy and reliability
- Use of up-to-date APS-technology (if possible space-qualified)
- Enhancement of functionality and reliability using filters and shutters based on LC/ TNC technology
- Development of experimental Flight-Model
- In-Orbit Flight Experiment and performance assessment

20

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Christopher Fuchs, EASA, IP, Space, Tech, on Micro-Tech, Technologies for Space, November 2003

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