

**MEMS – Sensor Bus
Application to the telemetry
subsystem
for the ARIANE 5 launcher**

**R&T CNES
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STATEMENT OF THE PROBLEM

TELEMETRY COST BREAK DOWN STRUCTURE

MEMS AND SMART SENSORS FOR THE TELEMETRY :

- POSSIBLE SOLUTION FOR MEMS

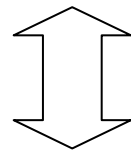
- POSSIBLE SOLUTION SMART SENSORS

CONCLUSION

OBJECTIVE OF THE STUDY

Use of New Sensors Technologies and Components for Cost Reduction. 2 New concepts envisaged.

- ❑ MEMS (micro electro-mechanical systems) = low cost sensors for the automobile market. Mostly analog ; sometimes including conditioning.



Seldom both

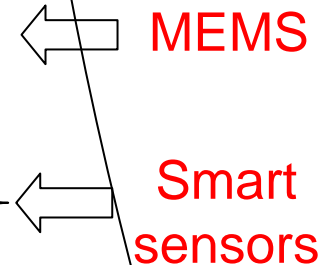
- ❑ Smart Sensors (IEEE 1451 standard) = with electronics inside = mostly related to the **Bus Sensor** Concept ; including New Functions such as self-identifiable sensors, self-compensated (offset, non linearities) sensors ; « plug and play » concept at the limit.

RECURRING COST FOR THE ARIANE 5 TELEMETRY

Telemetry stands for **20%** of the cost of avionics.

TM cost structure :

- ❑ Sensors = 20 %
- ❑ Harness & AIT(Assembly Integration & Test) = 35 %
- ❑ Electronics Boxes and Data Engineering = 45 %



MEMS

Smart sensors

DIFFICULTY with MEMS : INTERFACE CONSTRAINTS + VERY HARSH ENVIRONMENT

□ „Intrusive“ sensors (pressures (in majority), temperatures, tank levels) with strong leakage constraints.

Other sensors with mechanical interface constraints anyhow.

→ MEMS must be specially adapted for Ariane = overcosts

➡ POSSIBLE SOLUTION : STANDARD MECHANICAL INTERFACE

□ Cryo zones (He = 4 °k ; LH2 = 20 °k ; N2 = 77 °k ; LOX = 90 °k)
Hot spots (nozzles) > 1000 °c ...

➡ SOLUTION ? (Silicon Carbide technology = 600 ° C ?)

POTENTIAL CANDIDATES FOR MEMS REPLACEMENT

Out of **275** analog (operational) sensors per launcher,

➡ Potential candidates for MEMS (Non intrusive with acceptable temperature) amount to **50** ONLY.

➡ **But** they are often costly Vibrations sensors, accelerometers and gyrometers ...

ARIANE 5 / QUALIFICATION LEVELS OVERLOOK

SINE VIBRATIONS	1 cm 0-peak (5 - 16 Hz) 10 g 0-peak (16 - 60 Hz) 22,5 g 0-peak (60 - 200 Hz) 10 g 0-peak (200 - 2000 Hz)	
RANDOM VIBRATIONS	20 g rms (20 - 2000 Hz) 4 mn	Acoustics vibration test is generally replaced (except for large structures) by random vibration test.
ACOUSTICS VIBRATIONS	140 dB max (- 10 kHz)	
MEAN SHOCK 1/2 sine wave	50 g ; 11 ms	
PYRO SHOCK		Pyro shock are not applicable to electronics equipment , unless very close to the pyro shock (pyro devices)
ACCELERATIONS	7,5 g (3 mn)	
VACUUN	10^{-3} to 10^5 pa	Generally combined with thermics
THERMICS	- 40 (if P < 20 W) to + 70 °C (except cryo zones) ; 5 hours	

FOR ALL EQUIPMENT

NOTA 1 : Safety factor = 1,25 (7,5 g = 6 x 1,25)

NOTA 2 : electronics components range [-55° à +125°C]

EXAMPLES OF CANDIDATE MEMS

4 criteria taken into account

Sensor	Type	Fabricant	full scale	Sensitivity	Linearity - hysteresis	Temperature
Ariane Sensor						
candidate MEMS						
EGCS-AR5-50-DF3	accelerometer	entrant	+/- 5 g	360mV/g - 450 mV/g	0,4% full scale	-40/80°C
KXF00 - F50		Silicon Designs	5g	800mV/g	0,5% FS	-55/125°C
CE 254 M501	vibration at ordinary temperature	VIBROMETER	50g	50mV/g	1%	-45/125°C
MMA2202D		motorola	50g	40mV/g	?	-40/125°C
NE115 / A5 / 140-TD	differential pressure	NE-TECHNOLOGIE	140mbar	7,14 mV/mbar	< 0,15% FS	-40/100°C
3000 series		MERIT SENSOR	5 psi -350mb	75 mV	< 0,15%	-40/150°C

DIFFICULTY (worse than with MEMS) with SMART SENSORS : VERY HARSH ENVIRONMENT



- ❑ SENSOR BUS could reduce harness and AIT.
 - ❑ Smart (self compensated, ...) sensors could reduce the data engineering (sensors calibration, Data Base management, ...).
- ➔ **BUT** harsh environment is not appropriate for electronics inside SMART Sensors.

➔ **SOLUTION** : instead of « Smart sensor » use rather « **Smart interface** » = **CCS** (coupleur conditionneur standard), based on the IEEE 1451 standard.



EPC engine compartment (BM)
28 TM harness (out of 78 in the BM)
TO BE REPLACED BY 1 OR A FEW BUSES

tank I/F
7 sensors

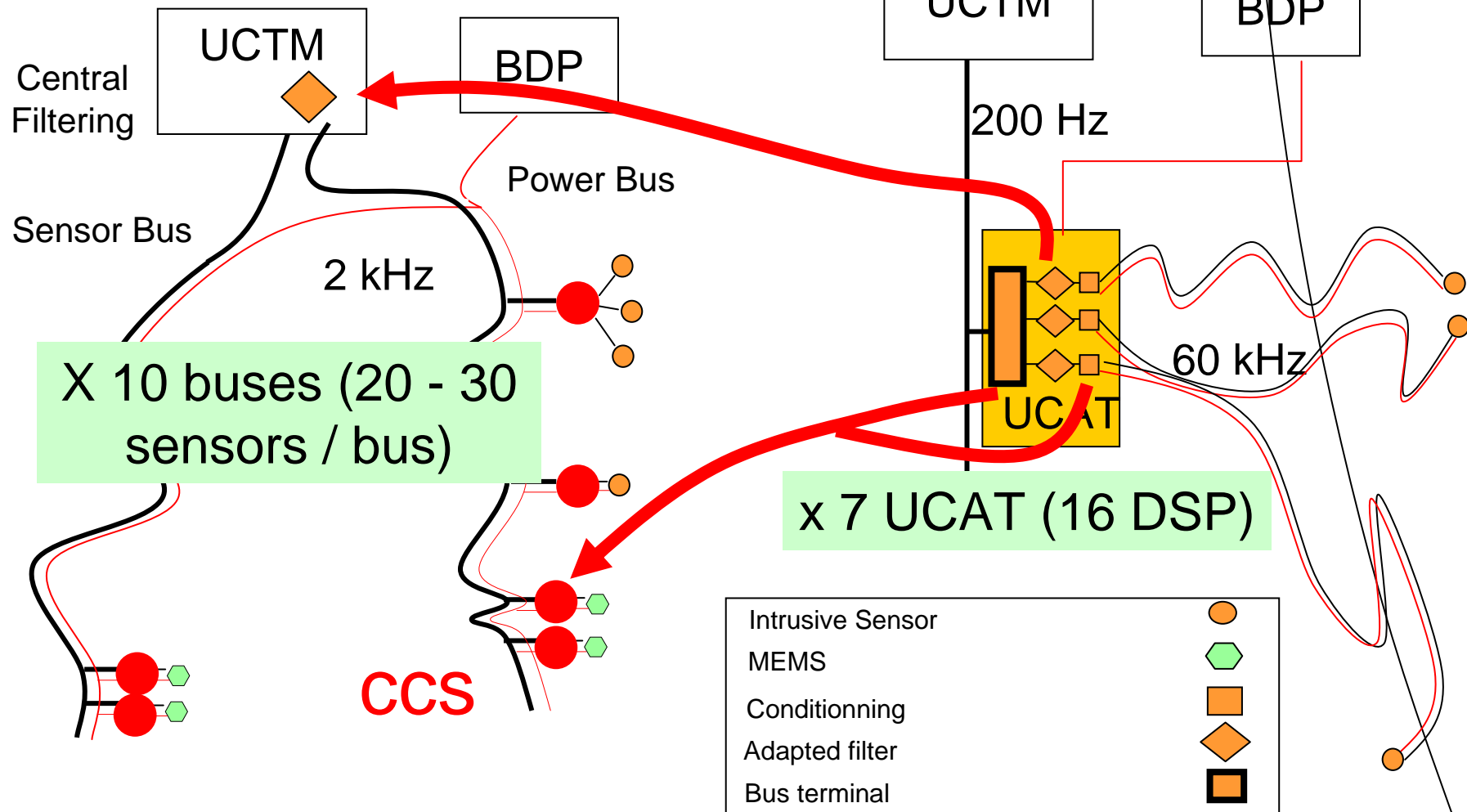
SNECMA I/F
3 x 27 sensors

3 to 4 wires / sensor

Acq.
Unit

BUS BASED TM ARCHITECTURE

CCS can cope with MEMS as well as with intrusive sensors or simple TOP sensors



ACQUISITION CHAIN MUST BE SIMPLIFIED

□ Today system =

- Standard acquisition at **high frequency** (60 kHz).
- Digital filtering (to frequency adapted to each sensor) needs costly DSP x 16.

□ **CCS** (coupleur-conditionneur standard) =

- Centralized digital filtering.
- Transmission **at medium frequency** via the Sensor Bus (4 KHz can meet all requirements, including shocks).



Suppression of Acquisition Units

CONDITIONS « SINE QUA NON » ON THE CCS

- ❑ COTS component if possible.
- ❑ Low cost (300 to 350 CCS per operational flight, including TOPS : regrouping needed)
- ❑ several CCS types required : without conditioning, thermocouple, ...
- + CCS **inside HARNESS** , close to sensor (but in « temperate » spot) in order to maximize the harness reduction.

⇒ CCS < **10 grams (tbc)**

CONCLUSION / EXPECTED OUTCOMES

- ❑ COST REDUCTION : $\cong 30\%$ (in part due to MEMS) of TM Recurring cost.
- ❑ **Drastic noise reduction** and reliability enhancement (less connectors).
- ❑ Harness mass reduction (> 10 kg for the upper composite) as well as electrical power reduction.
- ❑ **simplification of interfaces** between stages and sub-assemblies
 - ➔ more easy adding of sensors (less impacts on stage definition).
- ❑ Possibility of **adding a complete Bus** to investigate a local problem
 - ➔ not envisageable today.