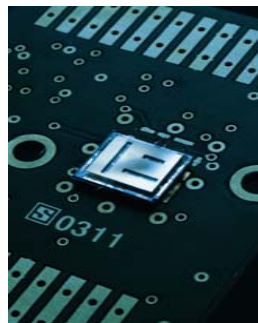




Development and Initial Characterisation of 2nd Generation MEMS Sun Sensor



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Pedersen, R. Fléron and Z. J. Davis

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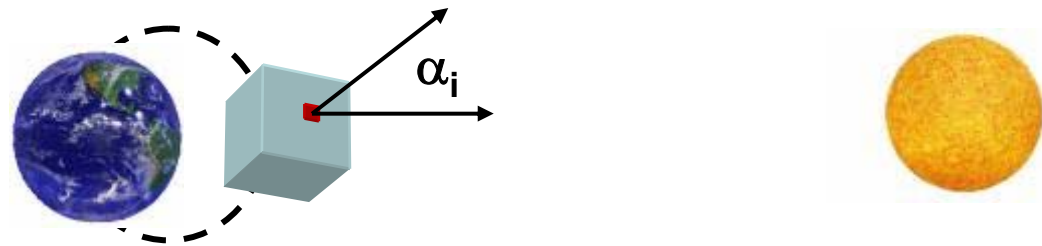
- Sun sensor principle
- General Fabrication Scheme
- 1st vs. 2nd Generation Performance Comparison
- Design of 2nd Generation
- Characterisation
- Status & Outlook



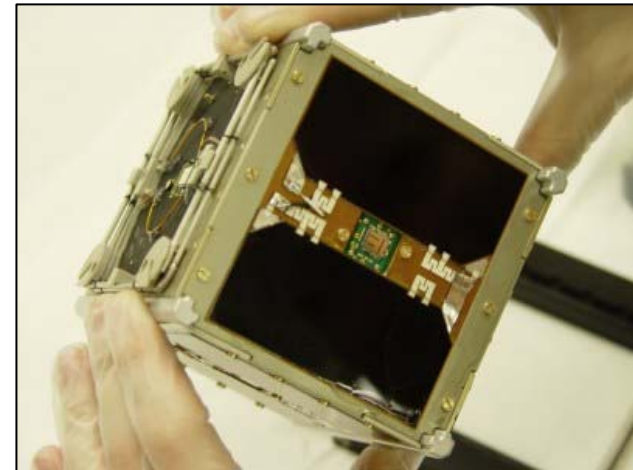
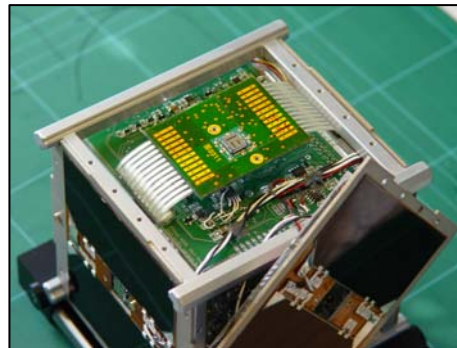
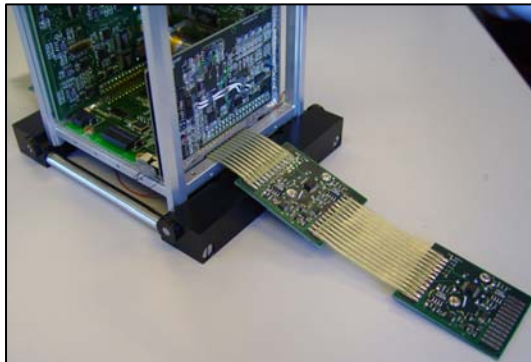
Attitude Determination

Basic Principle:

Detect the angle of the sun with respect to the sensor.

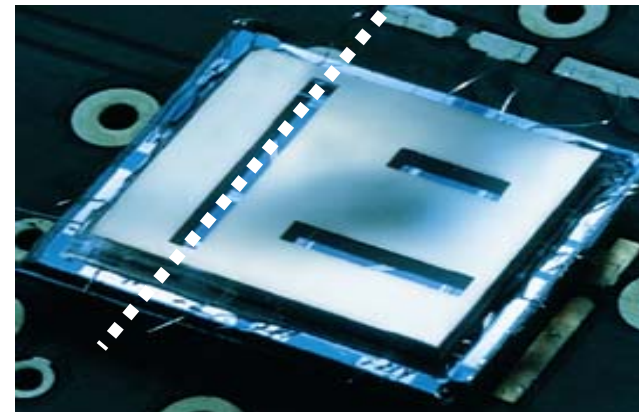
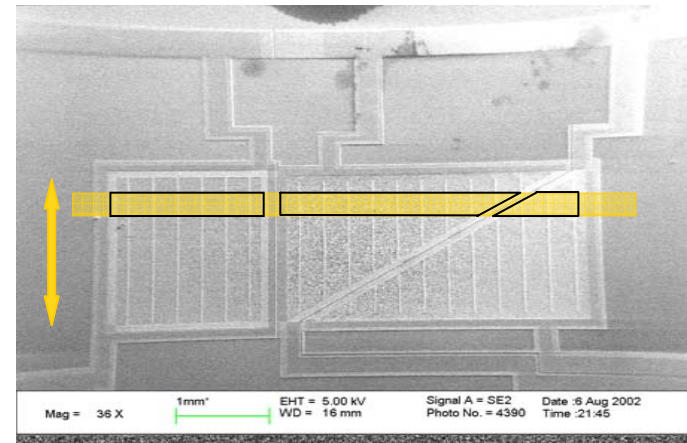
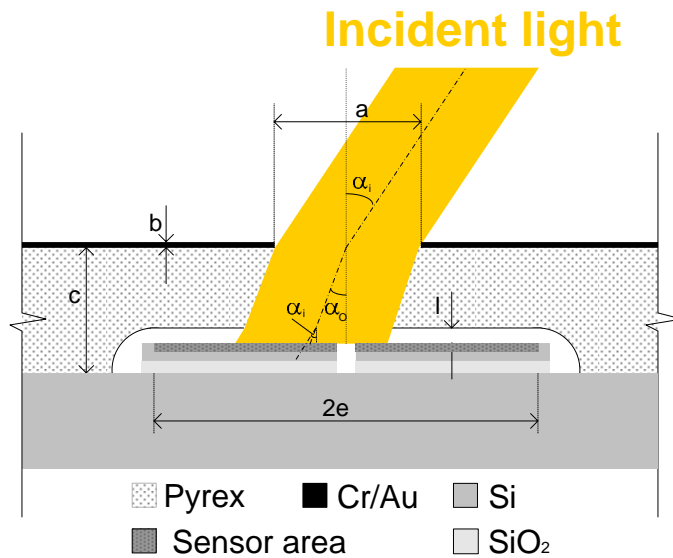


Implementation of MEMS in order to meet requirements
and constraints from CubeSat project.





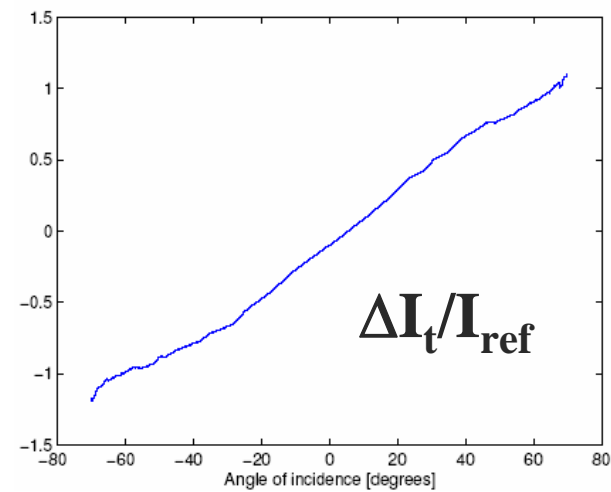
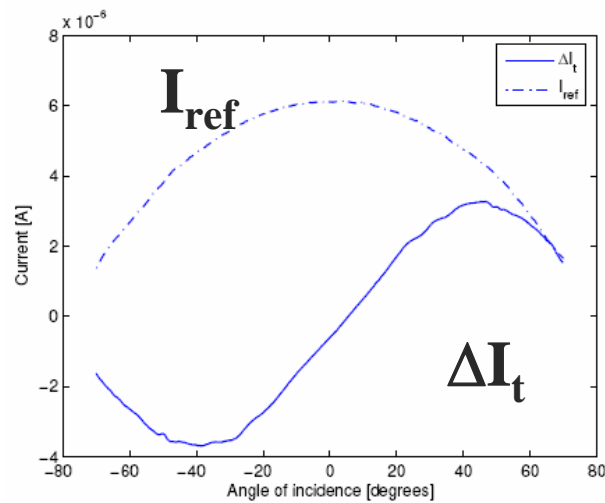
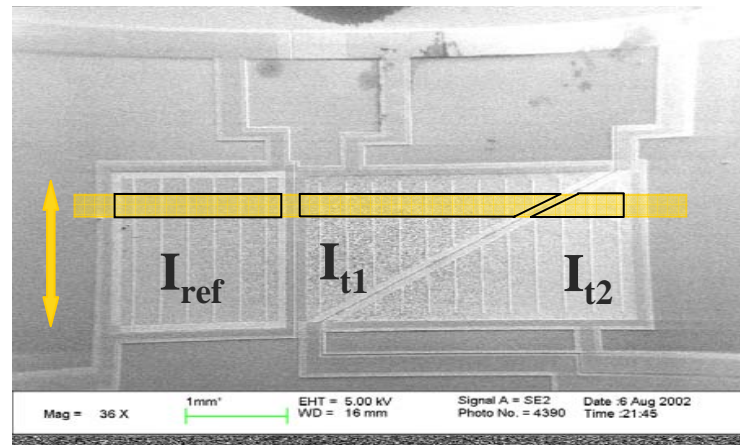
Transducer Principle



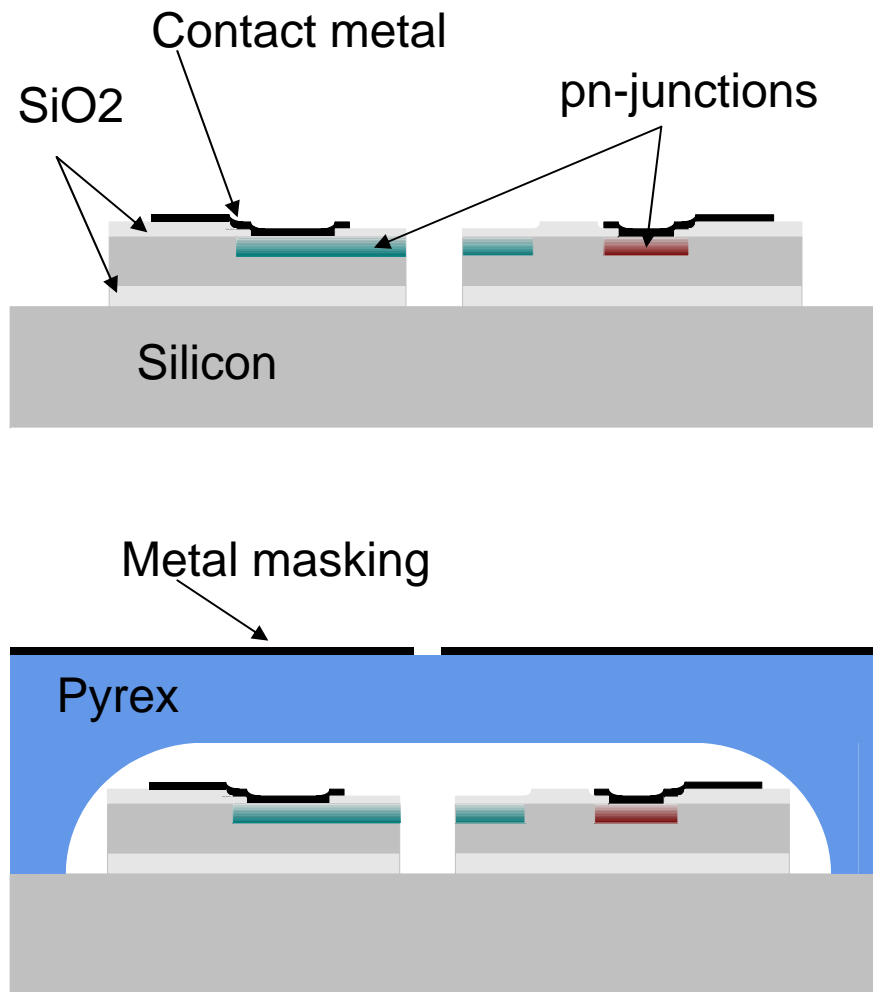
$$\frac{\Delta I}{I_{ref}} = \frac{\frac{E_e \cos(\alpha_x) \cos(\alpha_y)}{V} \eta (A_1(\alpha_i) - A_2(\alpha_i))}{\frac{E_e \cos(\alpha_x) \cos(\alpha_y) A_{ref} \eta}{V}} = \frac{A_1(\alpha_i) - A_2(\alpha_i)}{A_{ref}}$$



Transducer Principle



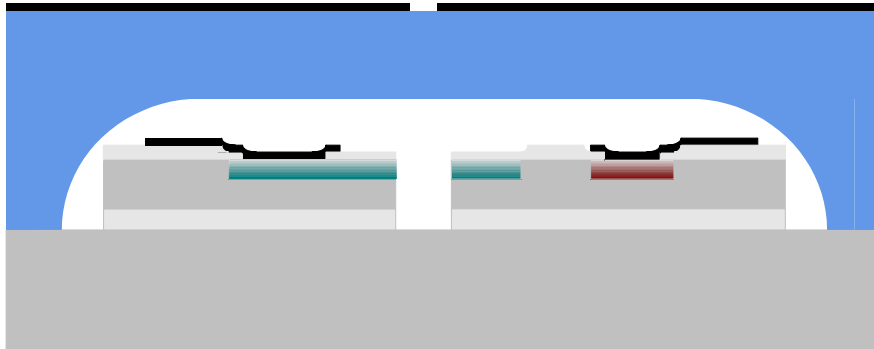
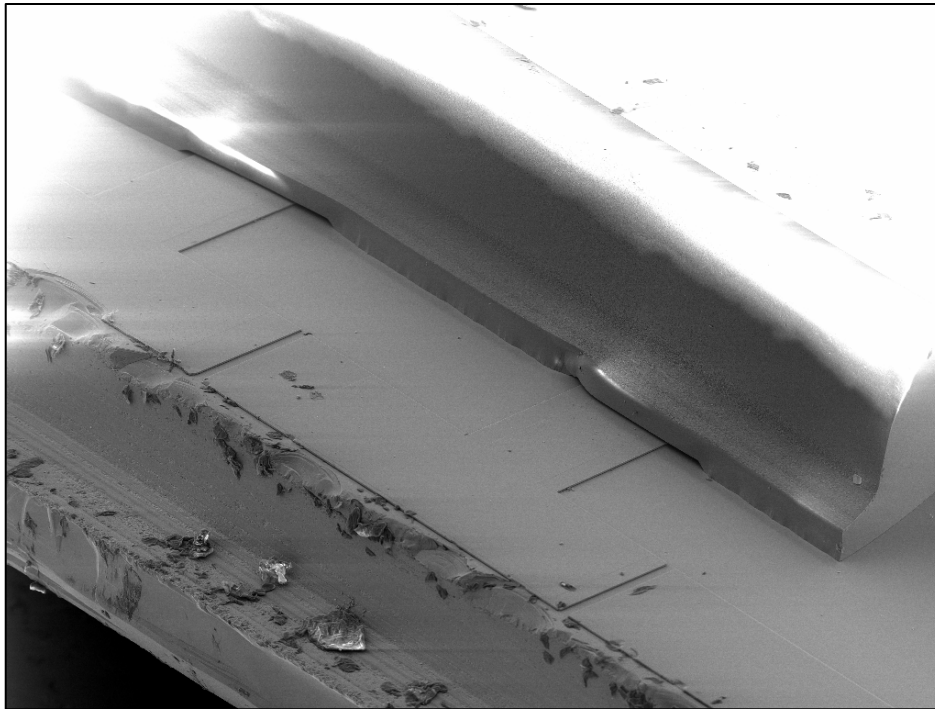
Fabrication



- SOI wafer
 - Ion implantation
 - Thermal oxidation
 - Metal contacts
 - RIE
- Pyrex wafer
 - Metal patterning
 - HF etch of Pyrex
 - Anodic bonding



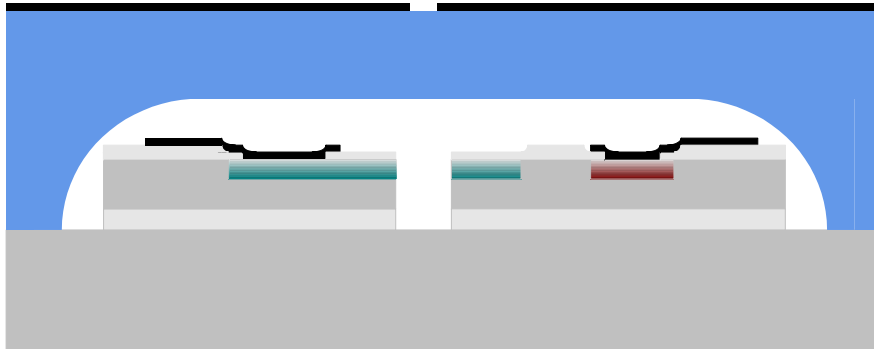
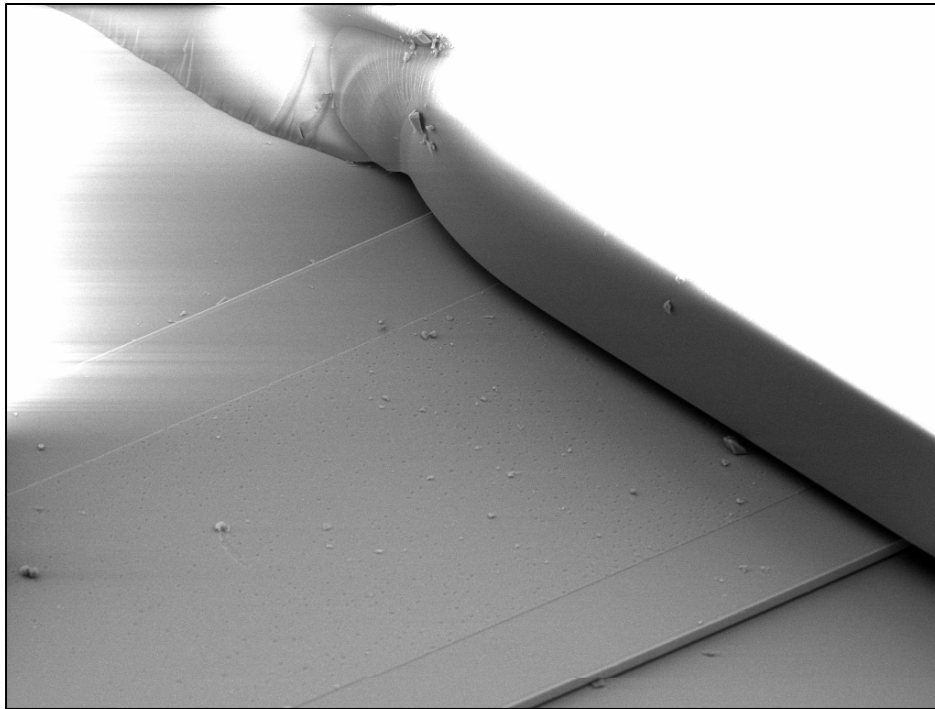
Fabrication



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Fabrication



- SOI wafer
 - Ion implantation
 - Thermal oxidation
 - Metal contacts
 - RIE
- Pyrex wafer
 - Metal patterning
 - HF etch of Pyrex
 - Anodic bonding

- General requirements
 - FOV > 110°
 - Resolution < 1°
 - High UV-sensitivity
 - Large signal-to-noise ratio

	1st Generation	2nd Generation
Dark Current	2 pA	0.8 pA – 0.8 nA
QE	4 % @ 450 nm	50-95 % @ 450 nm
Junction depth	660 nm	< 200 nm



Bulk Diode Designs

- pn-junction situated in the bulk (UV-absorption in the bulk depend on carrier lifetime)

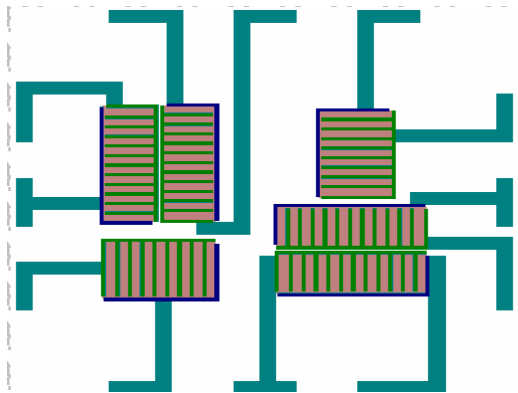


 **n+ contact**

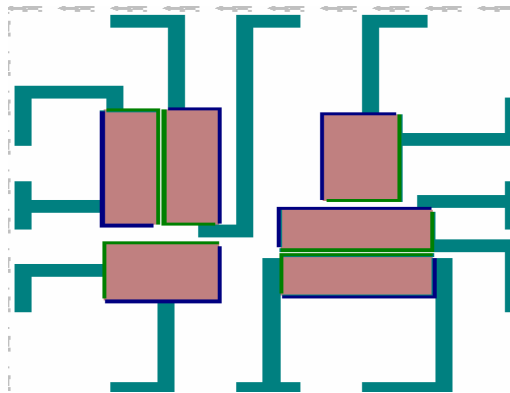
 **p+ contact**

 **n+ device**

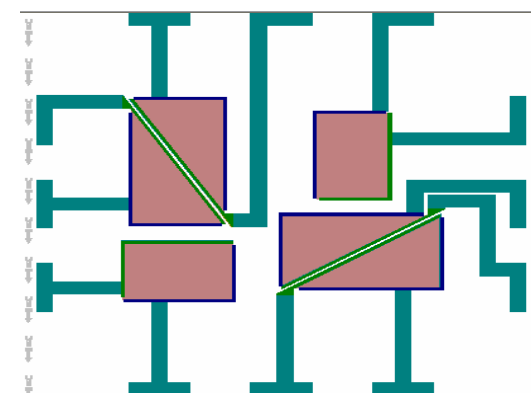
 **Metallization**



Finger



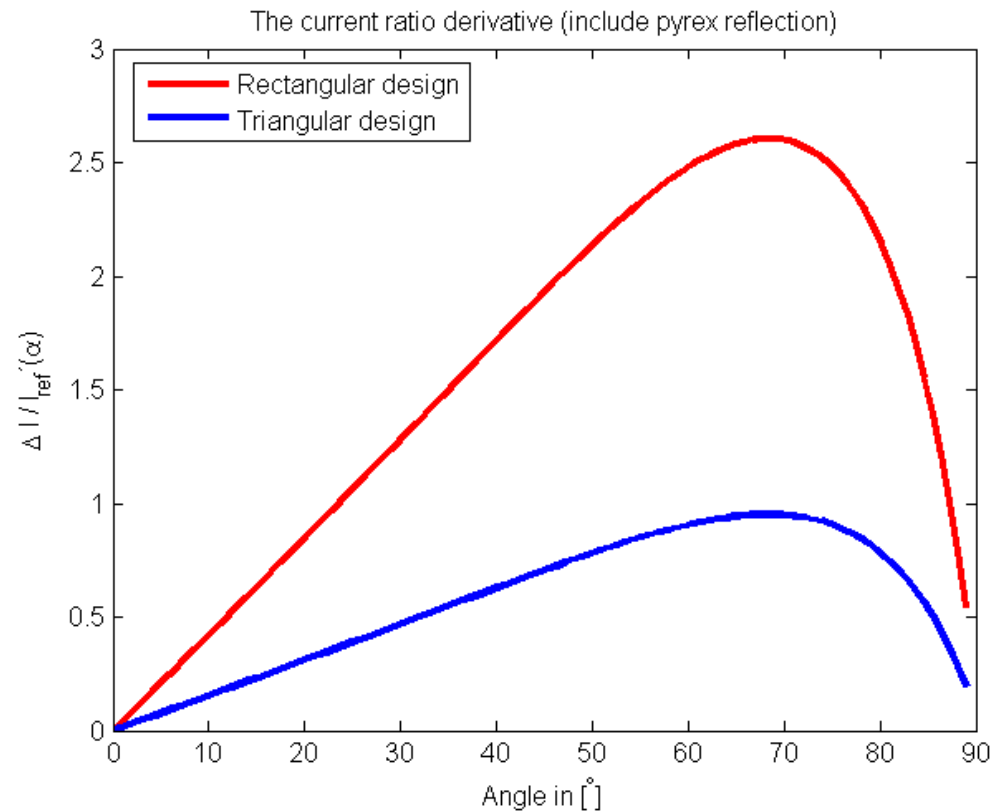
Rectangular



Triangular



Design Specifications

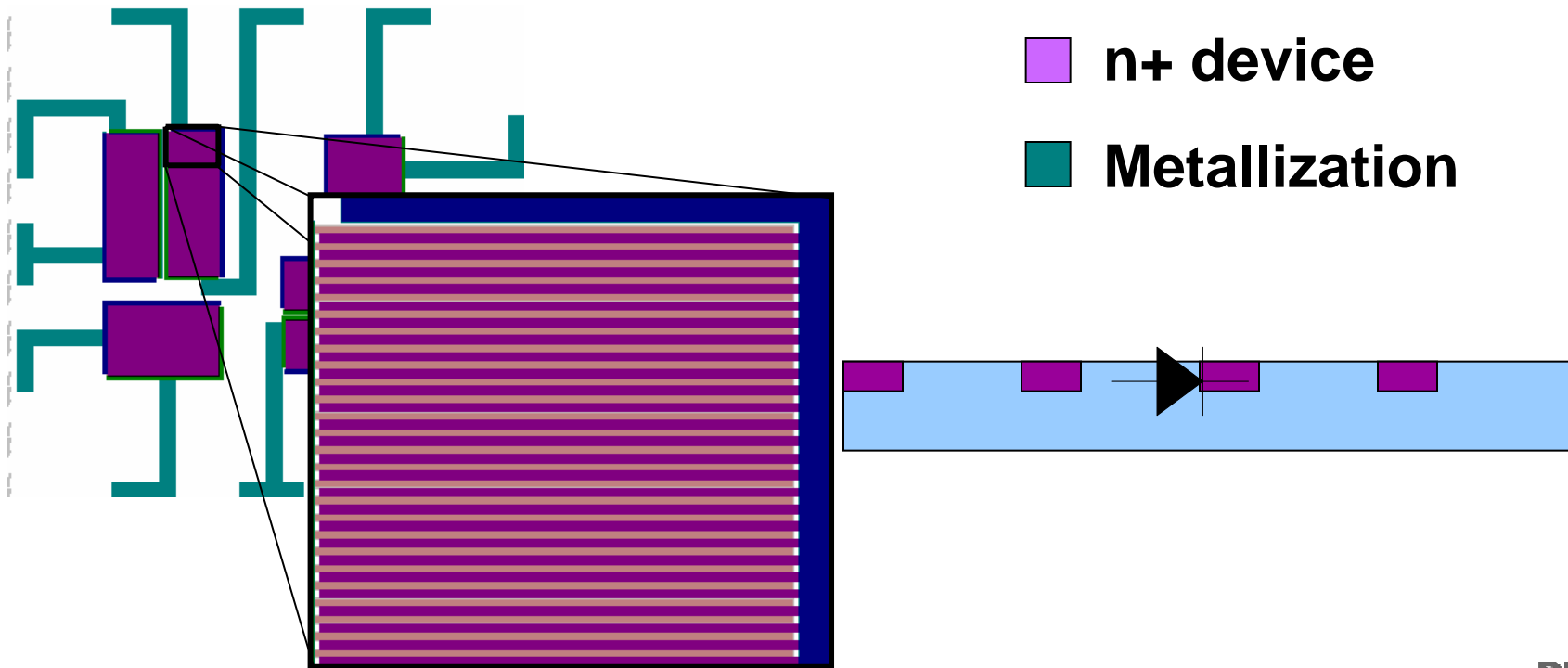




Surface Diode Design

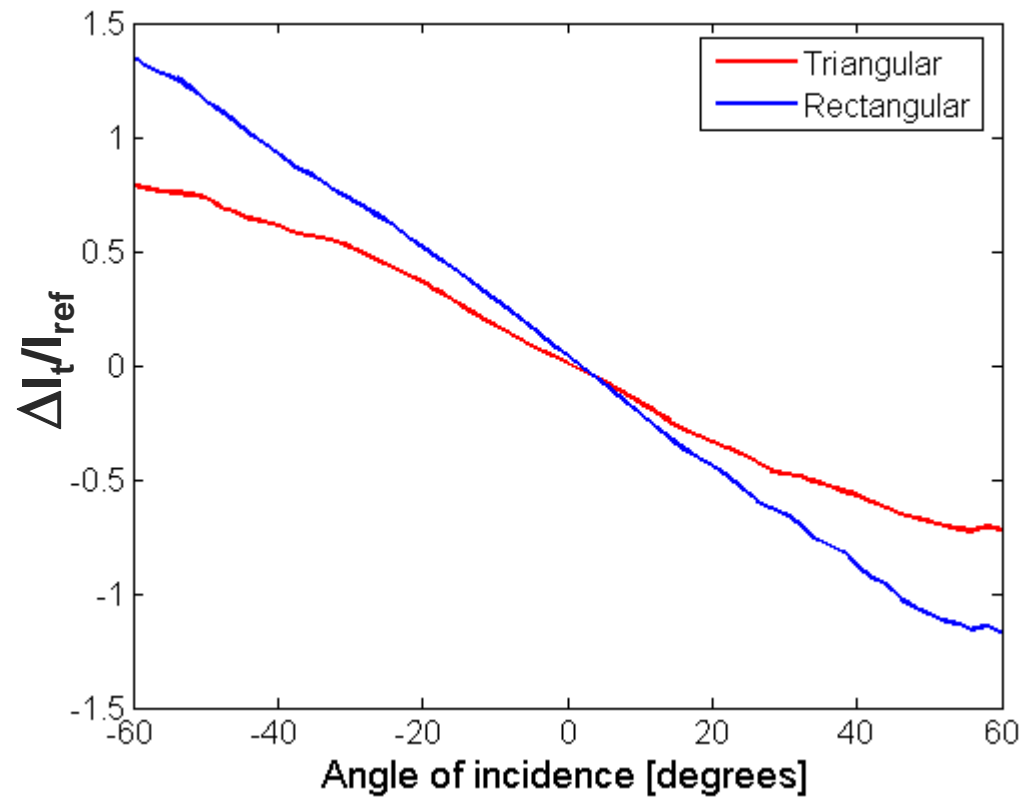
- ~ 70 % surface-diode coverage
(depletion layer extends all the way up to the surface)

- n+ contact
- p+ contact
- n+ device
- Metallization



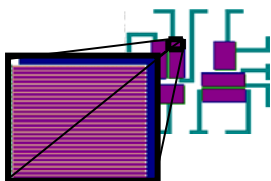
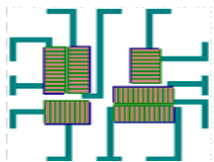
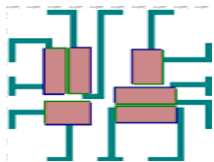
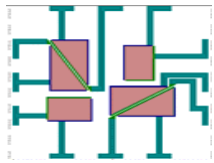


Angular Dependency





Nonlinearity FOV = 120°



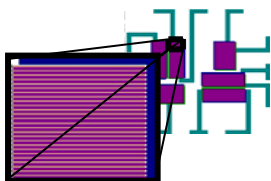
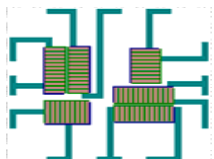
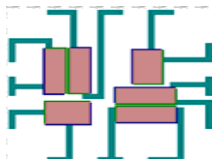
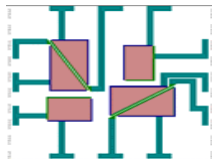
Chip	Sensitivity $\mu/\text{°}$	Linearity % FS	Accuracy ° (1σ)	Accuracy ° (3σ)
1T	17.3	9.1	± 2.5	± 7.4
4T	14.4	7.6	± 1.7	± 5.1
6T	14.3	9.5	± 2.0	± 5.9
1R	23.1	5.1	± 0.7	± 2.1
4R	22.2	5.7	± 0.8	± 2.4
6R	22.4	5.2	± 0.8	± 2.3
1F	20.9	5.4	± 0.9	± 2.7
4F	21.3	6.6	± 0.9	± 2.6
6F	22.7	5.5	± 0.9	± 2.7
1M	24.1	5.3	± 0.8	± 2.3
4M	24.0	5.8	± 1.0	± 2.9
6M	22.0	6.9	± 1.2	± 3.6

Theoretical estimation: $\pm 0.5^\circ$ FOV = 120°





Nonlinearity FOV = 60°



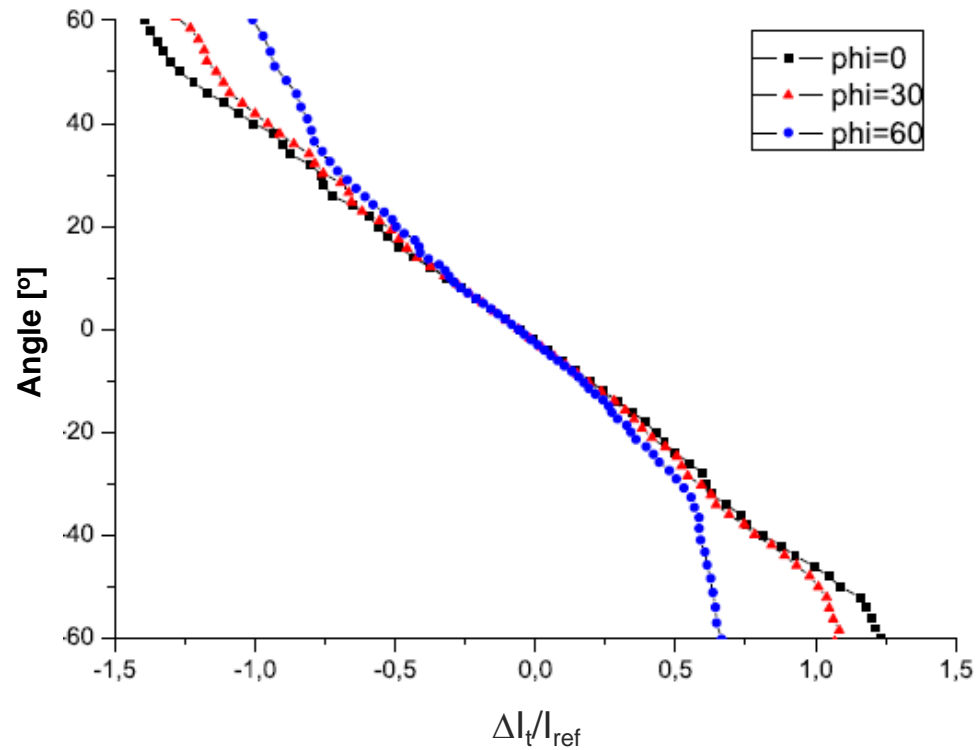
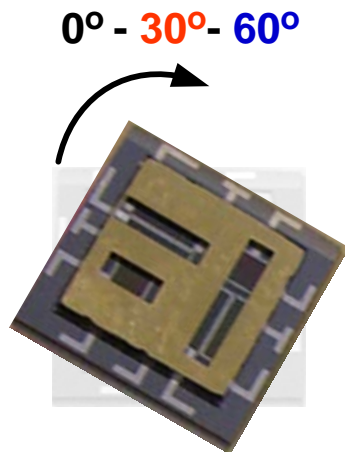
Chip	Chip Sensitivity	Linearity	Accuracy	Accuracy
	$\mu/^\circ$	% FS	$^\circ (1\sigma)$	$^\circ (3\sigma)$
1T	20.4	4.2	± 1.5	± 4.5
4T	17.0	2.3	± 0.3	± 0.9
6T	16.2	5.4	± 0.9	± 2.6
1R	24.4	3.7	± 0.5	± 1.4
4R	23.5	1.7	± 0.4	± 1.1
6R	23.9	2.1	± 0.3	± 0.8
1F	22.2	4.4	± 0.5	± 1.5
4F	23.1	3.1	± 0.4	± 1.1
6F	24.0	1.5	± 0.2	± 0.6
1M	28.0	1.3	± 0.2	± 0.5
4M	25.4	1.0	± 0.3	± 0.8
6M	25.3	2.4	± 0.4	± 1.1

Theoretical estimation $\pm 0.002^\circ$ FOV = 60°





Cross-Axis Sensitivity



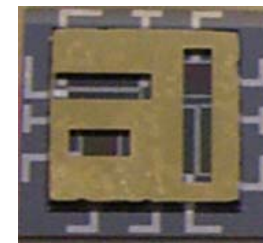
~ 5° accuracy for FOV = 60°



Comparison State-of-the-Art

NASA APS Quad Sun Sensor 2nd Generation

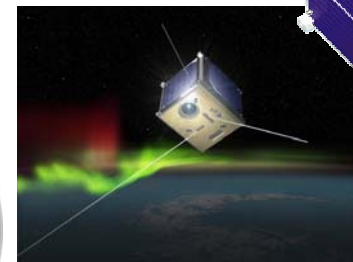
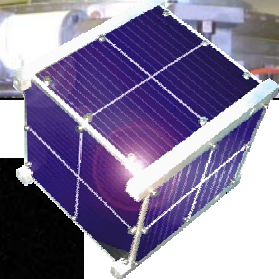
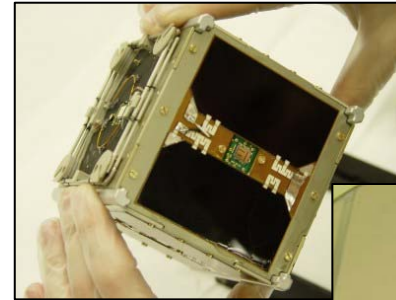
Type	Digital	Analog	Analog
Angular Accuracy	0.017°	1°	5° (1° possible)
FOV	60	60	60
QE	42 % @ 550 nm	N/A	75 % @ 550 nm
Size	4.2 cm ³	23.2 cm ³	~3.4 cm ³
Mass	9 g	36 g	3 g
Manufacturer	JPL	AeroAstro	MIC/DANCHIP





Flight History and Future

- DTUsat1 - Launched June 2003
- SSETI-Express - Launched October 2005
- COMPASS-1 – Scheduled for launch January 2008
- SwissCube – Launch planned mid-2008
- DTUsat2 – Launch planned: end-2008





Achievements

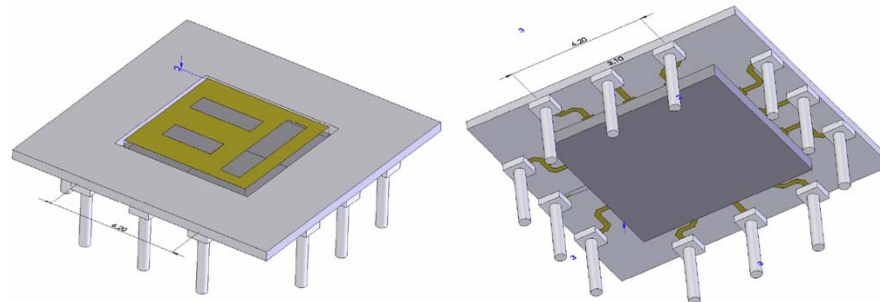
- Significantly higher performance obtained
 - QE ~50-95 %
- High UV sensitivity
 - Shallow pn-junctions
 - Integrated optical filter
- Larger signal-to-noise ratio
- Ceramic packaging

Challenges

- Issues with cross-axis sensitivity
 - Internal reflection
- Non linear fitting
- System integration

Prospects

- Total system
 - Accuracy: $< 1^\circ$
 - Mass: 3 g
 - Power: 5 mW





Acknowledgements

- Thor Ansbæk
- Ruichao Xu
- Julie Wulff
- Jack Larsen
- René Fléron
- Martin Pedersen
- Lars Alminde
- Anja Boisen
- DANCHIP staff
- Zachary Davis

